Low-Rank Univariate Sum of Squares Has No Spurious Local Minima ICCOPT 2022

Chenyang Yuan (Joint with Benoît Legat and Pablo Parrilo)

MIT



Tuesday 26th July, 2022



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Introduction

Semidefinite programming (SDP) is a powerful and expressive convex optimization method

Positive semidefinite variable $X \succeq 0 +$ linear constraints

Solved in polynomial time with interior point methods $(n \sim 10^3)$



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- Certain non-convex problems can be solved efficiently in practice with first-order methods $(n > 10^8)$
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- Algorithms that scale linearly necessary for working with "big data"

Can we apply these ideas to solving SDPs?

Burer-Monteiro methods for solving SDPs factor PSD variable $X = UU^T$, then perform local optimization on *non-convex* unconstrained problem

$$\begin{array}{rcl} \langle A_i, X \rangle &= b_i & \forall i \\ X &\succeq 0 & \longrightarrow & \min_U \sum_i (\langle A_i, UU^T \rangle - b_i)^2 \\ & & & & \\ & & & \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & & \\ & & & \\ & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & &$$

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When is non-convexity benign?

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SDP with *m* linear constraints, factorization $X = UU^{\top}$, where $U \in \mathbb{R}^{n \times r}$.

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Second-order critical points \implies **Global minima** (non-convexity benign):

- $r \ge n$ [BM05] (explicit counterexamples exist for r = n 1, m = n)
- $r \gtrsim \sqrt{m}$ with smoothed analysis [CM19], determinant regularization [BM05] or generic constraints [Bho+18]
- $r \gtrsim r^*$, where r^* maximum possible rank of SDP solution (matrix sensing [GJZ17], rotational synchronization [BBV16])

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Smaller r in factorization \rightarrow less benign landscape

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Can we get do better if the SDP has special structure?

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Given p(x), can we write it as a sum of squares? $p(x) = \sum_{i=1}^{r} u_i(x)^2$ Certifies that $p(x) \ge 0$, and can be formulated as a SDP:

$$p(x) = \vec{b}(x)^{\top} Q \vec{b}(x), \quad Q \succeq 0$$

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Q satisfying above constraints is called the Gram spectrahedron [Chu+16]



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Low-Rank Univariate Sum of Squares

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Previous work: rank needed for benign non-convexity $\sim \max$ rank of extreme points of Gram spectrahedron

Can we do better?

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Image credit: Tae Roh and Lieven Vandenberghe. (2006) Discrete transforms, semidefinite programming and sum-of-squares representations of nonnegative polynomials. SIAM J. on Optimization.

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Can we do better?

Univariate (trigonometric) polynomials:

$$p(x) = a_0 + \sum_{k=1}^{2d} a_k \cos(kx) \quad x \in [0, 2\pi]$$

Applications in signal processing, filter design and control



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Gram spectrahedra has extreme points of all ranks: $2 \le r \le \sqrt{d}$ [Sch22]

But always has rank-2 point! (Sum of 2 squares)

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Find sum of squares decomposition of p(x) by solving (equivalent to B-M):

$$\min_{\mathbf{u}} f_{p}(\mathbf{u}) = \left\| p(x) - \sum_{i=1}^{r} u_{i}(x)^{2} \right\|^{2}$$

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Theorem

For all nonnegative univariate polynomials $p(x) \in \mathbb{R}[x]_{2d}$ and any $r \geq 2$, if $\mathbf{u} \in \mathbb{R}[x]_d^r$ satisfies $\nabla f_p(\mathbf{u}) = 0$ and $\nabla^2 f_p(\mathbf{u}) \succeq 0$, then $f_p(\mathbf{u}) = 0$.

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First-order methods find sum of squares decomposition (non-convexity benign)

If we choose a suitable norm, $\nabla f_p(\mathbf{u})$ can be computed in $O(d \log d)$ time using Fast Fourier Transforms (FFTs)



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Define Sylvester map $\mathcal{A}_{\mathbf{u}}: \mathbb{R}[x]_d^r
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$$\mathcal{A}_{\mathbf{u}}(\mathbf{v}) = \mathcal{A}_{(u_1, u_2)}((v_1, v_2)) = u_1 v_1 + u_2 v_2$$

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Given an inner product $\langle\cdot,\cdot\rangle$ on polynomials with associated norm $\|\cdot\|$:

$$f_{p}(\mathbf{u}) = \left\| u_{1}^{2} + u_{2}^{2} - p \right\|^{2}$$
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Goal: For all **u** such that $\nabla f_p(\mathbf{u})(\mathbf{v}) = 0$ and $\nabla^2 f_p(\mathbf{u})(\mathbf{v}, \mathbf{v}) \succeq 0$ for all **v**, show that $f_p(\mathbf{u}) = 0$.

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To do so, for every $p \in \Sigma[x]_{2d}$ and $\mathbf{u} \in \mathbb{R}[x]_d^2$, find $\mathbf{v}_i \in \mathbb{R}[x]_d^2$ so that:

$$\nabla f_{\rho}(\mathbf{u})(\mathbf{v}_{0}) + \sum_{i=1}^{k} \nabla^{2} f_{\rho}(\mathbf{u})(\mathbf{v}_{i},\mathbf{v}_{i}) = -\left\|u_{1}^{2} + u_{2}^{2} - \rho\right\|^{2} = -f_{\rho}(\mathbf{u})$$

Geometric Interpretation

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Geometrically, we want to show that the only intersection between sets with zero gradient and PSD hessian is when $f_p(\mathbf{u}) = 0$.

For fixed **u**, these sets are convex (and can be represented by SDPs)!

$$\nabla f_{p}(\mathbf{u})(\mathbf{v}) \sim \langle \mathcal{A}_{\mathbf{u}}(\mathbf{v}), u_{1}^{2} + u_{2}^{2} - p \rangle = 0$$

$$\nabla^{2} f_{p}(\mathbf{u})(\mathbf{v}, \mathbf{v}) \sim \langle \mathcal{A}_{\mathbf{v}}(\mathbf{v}), u_{1}^{2} + u_{2}^{2} - p \rangle + \|\mathcal{A}_{\mathbf{u}}(\mathbf{v})\|^{2} \ge 0$$

$$- \|u_{1}^{2} + u_{2}^{2} - p\|^{2} = \nabla f_{p}(\mathbf{u})(\mathbf{v}_{0}) + \sum_{i=1}^{k} \nabla^{2} f_{p}(\mathbf{u})(\mathbf{v}_{i}, \mathbf{v}_{i})$$

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Main technical result: how to interpolate between these two cases

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Given p(x), q(x) of degree d, choose d + 1 points x_k

$$\langle p(x), q(x) \rangle = \sum_{k=1}^{d+1} p(x_k) q(x_k), \quad \|p(x)\|^2 = \sum_{k=1}^{d+1} p(x_k)^2$$

Valid inner product: when x_k distinct, if $||p(x)||^2 = 0$ then p(x) = 0.

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Given p(x), q(x) of degree d, choose d + 1 points x_k

$$\langle p(x), q(x) \rangle = \sum_{k=1}^{d+1} p(x_k) q(x_k), \quad ||p(x)||^2 = \sum_{k=1}^{d+1} p(x_k)^2$$

Valid inner product: when x_k distinct, if $||p(x)||^2 = 0$ then p(x) = 0.

Sum of squares using a sampled/interpolation basis studied by [LP04] and [CP17].

[[]LP04] Lofberg and Parrilo. "From Coefficients to Samples: A New Approach to SOS Optimization". 2004.

[[]CP17] Cifuentes and Parrilo. "Sampling Algebraic Varieties for Sum of Squares Programs". 2017. 🔍 🗆 🕨 🗸 🚍 🕨 🤘 🚍 🕨

Theorem holds for any inner product $\langle p(x), q(x) \rangle$ on polynomials, which should we choose?

Given p(x), q(x) of degree d, choose d + 1 points x_k

$$\langle p(x), q(x) \rangle = \sum_{k=1}^{d+1} p(x_k) q(x_k), \quad ||p(x)||^2 = \sum_{k=1}^{d+1} p(x_k)^2$$

Valid inner product: when x_k distinct, if $||p(x)||^2 = 0$ then p(x) = 0.

Sum of squares using a sampled/interpolation basis studied by [LP04] and [CP17].

How should we choose x_k ?

[[]LP04] Lofberg and Parrilo. "From Coefficients to Samples: A New Approach to SOS Optimization". 2004.

[[]CP17] Cifuentes and Parrilo. "Sampling Algebraic Varieties for Sum of Squares Programs". 2017. 🔍 🗆 🕨 🗸 🚍 🕨 🤘 🚍 🕨

Numerical Implementation

Compute sum of squares decomposition of degree 4n trigonometric polynomial

$$p(x) = a_0 + \sum_{k=1}^{2d} a_k \cos(kx) \quad x \in [0, \pi]$$

Using basis vectors evaluated at 4d + 1 points

$$B_k = [1, \cos(x_k), \dots, \cos(dx_k)]$$
$$x_k = \frac{k\pi}{d}, \quad k = 1, \dots, 4d + 1$$

Matrix-vector producted in $\nabla f_{\rho}(U)$ computed by FFT

$$abla f_{
ho}(U) = U^{ op} B \operatorname{Diag}(\left\| U^{ op} B_k
ight\|^2 -
ho(x_k)) B^{ op}$$





Image credit: Christos Papadimitriou, Sanjoy Dasgupta, and Umesh Vazirani. (2006) Algorithms

Numerical Results

Compute sum of squares decomposition for random trigonometric polynomial

Convergence rate for L-BFGS with random initialization



Numerical Results

Compute sum of squares decomposition for random trigonometric polynomial

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Results (stop at 10^{-7} relative error in **u**):

Degree of $p(x)$	10,000	20,000	100,000	200,000	1,000,000
Time (s)	6	9	53	160	1461
Iterations	530	632	1126	1375	2303

Conclusion

When does it make sense to solve non-convex formulations of convex problems? In our setting we can prove that non-convexity does not hurt us Near-linear time iteration cost with first-order methods in a benign landscape



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